After initializing GPS, I was at first unable to program in waypoint coordinates, until I realized my units were slightly different than the ones given in the assignment. Once I had the waypoint, I found that the “relative compass” of the GPS was not always consistent. Even when I was standing still and facing a constant direction, the arrow supposedly pointing me toward the waypoint fluctuated. In other words, even though the GPS knew where I was, it did not always know correctly the direction I was facing. Thus, sometimes I needed to rely on the “estimated distance” counter to ensure me that I was getting closer to the waypoint before I would completely trust the directional arrow.